

Application Serial No.: 09/926,541  
Reply to Office Action dated April 15, 2003

### AMENDMENTS TO THE CLAIMS

This listing of the claims will replace all prior versions, and listing, of claims in the application:

#### Listing of Claims:

1-14. (Canceled)

15. (Currently Amended) The robot according to claim 14 27, wherein the opening is configured to be formed by a pipe socket fixedly mounted on the manipulator.

16. (Currently Amended) The robot according to claim 14 27, wherein the ~~at least two holders include holder includes~~ a fastening means in the form of a curved collar.

17. (Currently Amended) The robot according to claim 16, wherein the ~~at least two holders are holder is~~ configured to be fixed by snap action with the curved collar.

18. (Currently Amended) The robot according to claim 16, wherein the ~~at least two holders are holder is~~ configured to be fixed with a hose clamp.

19. (Canceled)

20. (Currently Amended) The robot according to claim 19 27, wherein:  
the ~~at least two holders holder and the at least two lids lid have compatible shapes, and~~  
the ~~at least two holders holder and the at least two lids lid cover at least part of the at least one opening when mounted together.~~

21. (Currently Amended) The robot according to claim 19 27, wherein the ~~at least two holders holder and the at least two lids lid are configured to cover the opening and to form a tight seal of the opening.~~

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22. (Canceled)

23. (Currently Amended) The robot according to claim 14 27, the ~~at least two lids~~  
~~are~~ lid is configured to be divided into sections through at least one direction.

24. (Canceled)

25. (Currently Amended) The process according to claim 24 28, wherein ~~at least two~~  
~~lids are~~ at least one of the removable sections of lid is configured to be compatible with the ~~at~~  
~~least two holders~~ holder, and wherein the ~~at least two holders~~ holder and the ~~at least two lids~~  
lid are fixed in the opening to cover at least part of the ~~at least one~~ opening.

26. (Currently Amended) The process according to claim 25, wherein the ~~at least~~  
~~two holders~~ holder and the ~~at least two lids~~ lid are configured to cover the ~~at least one~~  
opening tight-fittingly when mounted together.

27. (New) An industrial robot comprising:

a control system including at least one cable set; and

a manipulator having an opening and a holder provided within said opening, said  
holder being detachably fixed along a section of an edge of said opening, said at least one  
cable set extending through said holder provided within said opening,

wherein said manipulator includes a lid configured to be detachably fixed to said  
edge, said lid having removable sections.

28. (New) A process for fastening in an industrial robot, the robot including a control  
system having at least one cable set, and a manipulator having an opening and a holder  
provided within the opening, the at least one cable set extending through the holder, said  
process comprising the steps of:

detachably fixing the holder along a section of an edge of the opening; and

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detachably fixing a lid to the edge, wherein the lid has removable sections.

29. (New) An industrial robot comprising:

a control system including at least one cable set; and

a manipulator having an opening and a holder provided within said opening, said holder having a collar with a U-shaped cross section that detachably connects to a section of an edge of said opening, said at least one cable set extending through said holder provided within said opening.

30. (New) The robot according to claim 29, wherein the opening is configured to be formed by a pipe socket fixedly mounted on the manipulator.

31. (New) The robot according to claim 29, wherein the holder is configured to be fixed with a hose clamp.

32. (New) The robot according to claim 29, wherein said manipulator includes a lid configured to be detachably fixed to said edge.

33. (New) The robot according to claim 32, wherein said lid has removable sections.

34. (New) The robot according to claim 32, wherein:

said holder and said lid have compatible shapes, and

said holder and said lid cover at least part of said opening when mounted together.

35. (New) The robot according to claim 32, wherein said holder and said lid are configured to cover said opening and to form a tight seal of said opening.